# A VARIATION ON THE RUBIK'S CUBE

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ABSTRACT. The Rubik's cube is a famous puzzle in which faces can be moved and the corresponding movement operations define a group. We consider here a generalization to any 3-valent map. We prove an upper bound on the size of the corresponding group which we conjecture to be tight.

# 1. INTRODUCTION

The Rubik's cube is a 3-dimensional toy in which each face of the cube is movable. There has been extensive study of its mathematics (see [7]). On the play side the Rubik's Cube has led to the creation of many different variants (Megaminx, Pyraminx, Tuttminx, Skewb diamond, etc.) The common feature of those variants is that they are all physical and built as toys.

Our idea is to extend the original rubik's cube to any 3-valent map M on any surface. To any face of the map we associate one transformation. The full group of such transformations is named Rubik(M) and we study its size and its natural normal subgroups.

A well studied extension [5, 4, 3, 8] of the Rubik's cube is the  $n \times n \times n$ -cube where the 3-lanes of the cubes are extended to n. There has also been interest [10] in cryptographic applications of Rubik's Cube. Thus the large class of groups that we build could be of wide interest in computer science.

In Section 2, we construct the Rubik's cube transformation of the map. In Section 3, we explain how to use existing computer algebra systems such as GAP in order to work with the Rubik's groups considered. In Section 4 we define several subgroups of the Rubik group and prove a bound on the size of the Rubik group in the oriented case. In Section 5 several possible extensions and further works are mentioned.

2. The construction of the Rubik group from a 3-valent map M

In this section we use M to denote a 3-valent map. By V(M), E(M), respectively Face(M), we denote the set of vertices, edges, respectively faces of M.

For any face F of M we define a side movement sm(M, F) to be a movement in one direction of a face F. This is illustrated in Figure 1. If the face contains pedges then the element sm(M, F) has order p.

For a set S of elements of a group G we define Group(S) to be the group generated by S. Using this we can define the Rubik's group:

$$Rubik(M) = Group(\{sm(M, F) \text{ for } F \in Face(M)\})$$



FIGURE 1. The action of the side movement



Rubik(Cube): Rubik's Cube.



Rubik(Dodecahedron): Megaminx

FIGURE 2. The Rubik construction for Cube and Dodecahedron

For the Cube and Dodecahedron this is known as Rubik's cube and Megaminx, see Figure 2 where the toy can be represented physically.

A corner of a map M is a pair (F, v) with v a vertex contained in a face F. A side edge of a map M is a pair (F, e) with e an edge contained in a face F. A 3-regular map M with v vertices has exactly e = 3v/2 edges. It will have 3v corners and 2e = 3v side edges. By Corner(M), we define the set of corners of M.

The face movement sm(M, F) acts on the set of corners and the set of side edges. This corresponds directly to the faces of the Rubik's cube.

#### 3. The computer Algebra side of things

We present the group Rubik(M) as a permutation group on the corners and side edges. This way of presenting the group follows [11] <sup>1</sup> where the standard Rubik's cube was considered.

For the example of  $Prism_3$  plane graph, we can number the corners and sideedges according to Figure 3. The side-movements generators of  $Rubik(Prism_3)$ can then be expressed as the following permutations:

gap> RubikPrism3:=Group([(31,35,33)(36,34,32)(3,19,11)(5,21,13)(8,24,16),

 $\begin{array}{c} (28,27,25)\,(30,28,26)\,(6,14,22)\,(4,12,20)\,(1,9,17)\,, \\ (1,6,8,3)\,(4,7,5,2)\,(17,35,16,25)\,(19,31,14,27)\,(18,36,15,26)\,, \\ (19,17,22,24)\,(18,20,23,21)\,(7,28,10,34)\,(8,27,9,33)\,(6,29,11,35)\,, \end{array}$ 

 $(9,14,16,11)\,(12,15,13,10)\,(1,31,24,29)\,(2,32,23,30)\,(3,33,22,25)])\,;$ 

The advantage of this approach is that there are very efficient implementations of permutation group algorithms (GAP) which can address in an efficient way many questions one may have about a permutation group.

<sup>&</sup>lt;sup>1</sup>See also an example in https://www.gap-system.org/Doc/Examples/rubik.html



FIGURE 3. Numbering of corners and side-edge of  $Prism_3$ 

One famous problem in Rubik's cube group theory is to find the minimal number of moves to go from one configuration to another, in other words to find the diameter of the Cayley graph of the group with the side moves as generators (see [9]). The GAP computer algebra software does not provide a solution to that problem, but it allows to express an element of the group in terms of the generators, that is find an expression, possibly not minimal.

More specific functionality for the computation is available in the GAP package [6].

### 4. Subgroups of Rubik(M)

The group Rubik(M) acts not only of the corners and side edges, but also on the vertices and edges. To represent those actions we use subscript such as  $sm(M, F)_{edge}$  and denote the corresponding group  $Rubik(M)_{edge}$ .

**Lemma 1.** Given a map M and a face F we have:

- (i) The signature of  $sm(M, F)_{side \ edge}$  is 1.
- (ii) The signature of  $sm(M, F)_{vertex}$  is equal to the signature of  $sm(M, F)_{edge}$ .

*Proof.* (i) If F is a face with p sides then F contains p side edges (F, e), each side edges is adjacent to another side edge  $(F_e, e)$ . The side generator sm(M, F) has one cycle formed by the side-edges (F, e) and another cycle formed by the side edges  $(F_e, e)$ . Each of those cycles has the same length and so the signature of sm(M, F) acting on the side-edges is 1.

(ii) If F is a face with p sides then it contains p edges and p vertices. The action on each of them is a cycle of length p. So their signature is the same.  $\Box$ 

We now consider what additional properties can be obtained if the map M is oriented.

**Definition 1.** Assume M is an oriented map. Every vertex v of M is contained in 3 corners  $C_v = \{c_1, c_2, c_3\}$ . Since M is orientable, we can assume that  $C_v$  is oriented in the direct way.

We denote by OrMap(M) the set of permutations of the corners that preserve the triples and their orientation.

Given two corners c, c' we call sh(c, c') the number k of rotations r by  $2\pi/3$  such that  $r^k(c) = c'$ .

The orientability of the map will allow us to restrict the possibilities of mapping the corners. We need the OrMap(M) set of map in order to define some properties

below for the Rubik's cube group. The shift is more complicated. If a vertex v has  $C_v = \{c_1, c_2, c_3\}$  in direct orientation then we have e.g.  $sh(c_i, c_i) = 0$ ,  $sh(c_1, c_2) = 1$  and  $sh(c_1, c_3) = 2$ .

**Theorem 1.** Let M be an oriented map. The following holds:

(i) For c, c', c'' corners we have  $sh(c, c'') = sh(c, c') + sh(c', c'') \pmod{3}$ 

(ii) For a function  $\phi: V(M) \to Corner(M)$  such that  $\phi(v)$  is a corner of V and a function  $f \in OrMap(M)$  the expression

$$\sum_{\in V(M)} sh(f(\phi(v)), \phi(f(v)))$$

is independent of  $\phi$  and denoted sh(f).

(iii) If  $f, g \in OrMap(M)$  then we have

$$sh(f \circ g) = sh(f) + sh(g) \pmod{3}$$

(iv) sh is a non-trivial function on OrMap(M).

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(v) For  $f \in Rubik(M)$  we have  $sh(f) = 0 \pmod{3}$ .

Proof. (i) The equality follows by additivity of the rotational shift.

(ii) Let  $\phi$ ,  $\phi'$  two such functions. Then we define  $r(v) = sh(\phi(v), \phi'(v))$ . Define first  $a(\phi) = \sum_{v \in V(M)} sh(f(\phi(v)), \phi(f(v)))$ , we then have:

$$\begin{array}{ll} a(\phi') &=& \sum_{v \in V(M)} sh(f(\phi'(v)), f(\phi(v)) + sh(f(\phi(v)), \phi(f(v))) \\ &+ sh(\phi(f(v)), \phi'(f(v))) \\ &=& a(\phi) + \sum_{v \in V(M)} sh(f(\phi'(v)), f(\phi(v)) + \sum_{v \in V(M)} sh(\phi(f(v)), \phi'(f(v))) \\ &=& a(\phi) + \sum_{v \in V(M)} sh(\phi'(v)), \phi(v)) + \sum_{v \in V(M)} sh(\phi(f(v)), \phi'(f(v))) \\ &=& a(\phi) + \sum_{v \in V(M)} sh(\phi'(v)), \phi(v)) + sh(\phi(v)), \phi'(v)) \\ &=& a(\phi) + \sum_{v \in V(M)} sh(\phi'(v)), \phi'(v)) \\ &=& a(\phi) \end{array}$$

The equality  $sh(f(\phi'(v)), f(\phi(v))) = sh(\phi'(v), \phi(v))$  comes from the fact that f preserves the orientation of the corners. The equality  $\sum_{v \in V(M)} sh(\phi(f(v)), \phi'(f(v))) = \sum_{v \in V(M)} sh(\phi(v), \phi'(v))$  comes from the fact that f is permuting the vertices of M.

(iii) Let f and g be two such mappings. We then have

$$\begin{array}{lll} sh(f \circ g) & = & \sum_{v \in V(M)} sh(f(g(\phi(v))), \phi(f(g(v)))) \\ & = & \sum_{v \in V(M)} sh(f(g(\phi(v))), f(\phi(g(v)))) + sh(f(\phi(g(v))), \phi(f(g(v)))) \\ & = & \sum_{v \in V(M)} sh(g(\phi(v)), \phi(g(v))) + \sum_{v \in V(M)} sh(f(\phi(v)), \phi(f(v))) \\ & = & sh(g) + sh(f) \end{array}$$

We have used that f preserves orientation and the fact that g permutes the vertices in our rewriting.

(iv) Let us select a vertex v of M with  $C_v = \{c_1, c_2, c_3\}$ . We set  $f(c_i) = c_{i+1}$  for  $c_i \in C_v$  and f(c) = c otherwise. We find that sh(f) = 1.

(v) Let F be a face of M. We select a function  $\phi$  such that phi(v) = (F, v) for v and vertex contained in F and an arbitrary choice on other vertices.

Setting f = sm(M, F) we have

$$sh(f) = \sum_{v \in F \cap V(M)} sh(f(\phi(v)), \phi(f(v)))$$

It is easy to see that  $\phi(f(v)) = f(\phi(v))$  for  $v \in F \cap V(M)$ . Thus we get sh(f). Since the side movement generate Rubik(M), by (iii) we get that for all  $f \in Rubik(M)$ , sh(f) = 0.

**Theorem 2.** We have a sequence of group homomorphisms:

$$\begin{aligned} Rubik(M) &= Rubik(M)_{corner,side\ edge} \rightarrow Rubik(M)_{corner,edge} \\ &\rightarrow Rubik(M)_{corner} \rightarrow Rubik(M)_{vertex} \end{aligned}$$

*Proof.* The equality  $Rubik(M) = Rubik(M)_{corner,side edge}$  comes from the definition of the Rubik group. If the group acts on the side-edges, then it acts on the edges and so we get the map  $Rubik(M)_{corner,side edge} \rightarrow Rubik(M)_{corner,edge}$ . Dropping the edge action gets us the mapping to  $Rubik(M)_{corner}$ . Finally, a vertex is contained in 3 faces and so in 3 corners. This defines a mapping from  $Rubik(M)_{corner}$  to  $Rubik(M)_{vertex}$ .

We define following subgroups from those homomorphisms:

$$\begin{cases} G_1(M) = Ker(Rubik(M)_{corner,side\ edge} \to Rubik(M)_{corner,edge}) \\ G_2(M) = Ker(Rubik(M)_{corner,edge} \to Rubik(M)_{corner}) \\ G_3(M) = Ker(Rubik(M)_{corner} \to Rubik(M)_{vertex}) \end{cases}$$

We can now use the above decomposition in order to get a conjectural description of Rubik(M).

**Theorem 3.** Given an oriented map M the following holds:

(i)  $G_1(M)$  is a subgroup of  $\mathbb{Z}_2^{|E(\hat{M})|-1}$ 

(ii)  $G_2(M)$  is a subgroup of the alternating group  $A_{|E(M)|}$ .

(iii)  $G_3(M)$  is a subgroup of  $\mathbb{Z}_3^{|V(M)|-1}$ 

(iv)  $Rubik(M)_{vertex}$  is a subgroup of  $A_{|V(M)|}$  if all faces of M have odd size and a subgroup of  $S_{|V(M)|}$  otherwise.

*Proof.*  $G_1(M)$  is formed by all the transformations that preserve all corners and edges but may switch a side edge  $(F_1, e)$  into another side edges  $(F_2, e)$ . Since every edge is contained in two faces, this makes  $G_1(M)$  a subgroup of the commutative subgroup  $\mathbb{Z}_2^{|E(M)|}$ . The group  $\mathbb{Z}_2^{|E(M)|}$  contains some elements that switch just two side-edges and are thus of signature -1. Thus by Lemma 1.(i)  $G_1(M)$  is isomorphic to a strict subgroup of  $\mathbb{Z}_2^{|E(M)|}$ .

 $G_2(M)$  is formed by the transformations that preserves the corners but will permutes the edges. Thus we have that  $G_2(M)$  is a subgroup of  $S_{|E(M)|}$ . Since elements of  $G_2(M)$  preserves all vertices, the signature of their action is 1. By Lemma 1.(ii) the signature of their action on edges is also 1. Therefore  $G_2(M)$  is a subgroup of  $A_{|E(M)|}$ .

 $G_3(M)$  is formed by all transformations that preserves the vertices but may permutes the corners. Since the corners are oriented, the operation on each vertex v may be encoded by an element  $x_v$  of  $\mathbb{Z}_3$ . By Theorem 1.(v) we have sh(f) = 0for each  $f \in G_3(M)$ . Thus we get  $\sum_{v \in V(M)} x_v = 0$ . This means that  $G_3(M)$  is a subgroup of  $\mathbb{Z}_3^{|V(M)|-1}$ .



FIGURE 4. The Pyraminx toy

The side movements sm(M, F) act on the vertices. For a face of size p the signature is  $(-1)^{p-1}$ . Thus if all faces of M have odd size then all side movements have signature 1 and  $Rubik(M)_{vertex}$  is a subgroup of  $A_{|V(M)|}$ . If there is a face of even size then it is a subgroup of  $S_{|V(M)|}$ .  $\square$ 

**Conjecture 1.** ("First law of cubology") Given an oriented map M with v vertices and e edges the following holds:

(i)  $G_1(M)$  is isomorphic to  $\mathbb{Z}_2^{|E(M)|-1}$ 

(i)  $G_1(M)$  is isomorphic to  $\mathbb{Z}_2^{(M)}$ (ii)  $G_2(M)$  is isomorphic to  $A_{|E(M)|}$ . (iii)  $G_3(M)$  is isomorphic to  $\mathbb{Z}_3^{|V(M)|-1}$ (iv)  $\operatorname{Rubik}(M)_{vertex}$  is isomorphic to  $A_{|V(M)|}$  if all faces of M have odd size and  $S_{|V(M)|}$  otherwise.

This conjecture has been checked for many plane graphs e.g. the ones with at most 40 vertices and faces of size 6 or p with  $3 \le p \le 5$ . This Theorem is proved for the cube case in [7, Theorem 11.2.1], [1, Section 2.4] and [2, Theorem 1.3.24].

### 5. Possible extensions and open problems

There are many possible extensions of this work. First we could consider other constructions so as to generalize all the existing Rubik's cube variant toys to a combinatorial setting. For example the Pyraminx (Figure 4) does not belong to the family described here.

Proving the conjecture on the description of Rubik(M) appears to be a difficult problem as the cube proofs seem difficult to generalize. Another research question is to consider the classification of elements of order 2 of Rubik(M) as well as the determination of the maximal order of the elements of Rubik(M) (see [2] for the Cube case).

Much time and energy has been spent on playing on Rubik's cube and this could be done as well for Rubik(M). One would have to forget the physical part and accept playing on a smartphone, which could be programmed reasonably easily. For plane graph this could be represented by a Schlegel diagram and for toroidal maps, we could use a plane representation with a group of symmetries.

Classifying the 3-valent graphs for which Rubik(M) may be constructed physically is also an interesting problem.

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